

## T600 TACHOMETER

MultiTasker - a measurement & monitoring instrument with 2 frequency and 1 analog inputs

### Features

- High accuracy speed measurement: 0.002% for limits and 0.1% referenced to 20 mA
- 2 frequency + 1 analog + 2 binary inputs
- Direction and creep detection
- Temperature measurement with PT100
- 2 current, 4 relay and 2 Open Collector outputs
- Sensor monitoring for all sensor technologies
- Ethernet interface - configuration via Java™ based software
- Extensive parameter and limit setting possibilities
- Programmable logical, diagnostic and measurement functions
- Plug in terminals

### The T600 Advantage

- Fast 8 ms relay reaction time on over speed
- 4 parameter sets each with 6 System Limits for almost limitless applications
- Logical limit combinations save relays & wiring
- Acceleration measurement
- Compatible with all popular sensor types

### Typical Applications

- Micro turbine speed measurement and over speed protection
- Diesel engine start control and protection
- Dual turbocharger speed measurement
- Universal tachometer

# T600

Tachometer

## 2 Channel Tachometer with 4 Relays, 2 Open Collector and two 0/4-20mA Outputs:

<b>Type and part numbers</b>	AC version:	T601.50	Part number: 384Z-05602
	DC version:	T601.10	Part number: 384Z-05603

### Technical Data

<b>Measurement range</b>	0.025 Hz... 50.00kHz		
<b>Measuring time</b>	Configurable min. measurement time (tM): 2/5/10/20/50/100/200/500 ms, 1/2/5s.		
<b>Reaction time</b>	Current output:	Typical tM + 4.1 ms	Maximum Input period + tM + 4.1 ms
	Relays:	Typical tM + 6 ms	Maximum Input period + tM + 6 ms
<b>Accuracy</b>	Limits / inputs	Frequency: 0.002% Current: 0.025% Temperature: 0.5 °C	
	Current output	0.1% referenced to 20mA or the end value Max 0.2 % from measuring value + 2 LSB (-40°...+70°C)	
<b>Sensor inputs (2)</b>	To measure frequency signals (speed sensors)		
	<b>Frequency range</b>	0.025 Hz to 50 kHz	
	<b>Trigger levels</b>	Selectable by software: Fixed at 3 V or adaptive from either 20 mVrms or 180 mVrms	
	<b>Sensor supply</b>	+14 V ±0.5 V, max 35 mA, short circuit proof	
	<b>Sensor monitoring</b>	3 wire sensors:	Programmable current consumption limits of 0.5...35mA.
		Electromagnetic sensors:	Open circuit detection
	<b>Analysis functions</b>	Creep, Direction, Math (e.g. subtraction, percentage, acceleration, variance)	
<b>Analog input (1)</b>	To measure current or temperature		
	Type	0...20 mA / 4...20 mA / PT100 for temperature	
	Input impedance (passive input)	50 Ohm	
	Resolution	12 bit corresponding to 1:4096	
	Analysis functions	Math (e.g. acceleration, variance)	
<b>Binary inputs (2)</b>	Isolated inputs for binary signals		
	<b>Levels</b>	Low: < +5 V	High: > +15 V (software selection of active Low or High)
	<b>Functions</b>	External selection of controls (parameter sets)	
		Combination in System Limit	Reset for relay, creep and memory
<b>Data I/O</b>	Configuration and monitoring	Ethernet interface	
	Controlling and monitoring	CAN	
<b>Supply</b>	AC version:	90...264 VAC max 14 W / 120...370VDC	
	DC version:	18...36 VDC max 6.8 W	
<b>Relays (4)</b>	To treat the status of System Limits and sensor		
	<b>Limits</b>	4 parameter sets each with 6 System Limits (AND / OR combined values)	
	<b>Hysteresis</b>	Freely programmable upper and lower set-points for each limit	
	<b>Function</b>	Latching / inversion (fail safe)	
	<b>Contacts</b>	Change-over: 230 VAC / max. 0.45 A 125 VAC / max. 1 A 30 VDC / max. 2 A	
<b>Open collector outputs (2)</b>	Isolated outputs of sensor frequencies: programmable x1, x2 or x4 (subject to 2 channel phase shift)		
		Can also react on System Limits, see above	
	<b>Function</b>	Latching / inversion (fail safe)	
	<b>Contacts</b>	Umax = 36 Vdc Imax = 30 mA	
<b>Analog outputs (2)</b>	Isolated current output to treat information of sensor 1, 2, analog in or of the math result		
	<b>Range</b>	From - 99999 to + 999999 free programmable start and end value	
	<b>Type</b>	0...20 mA / 4...20 mA	
	<b>Maximum load</b>	500 Ohm corresponding to a maximum of 10 V	
	<b>Resolution</b>	14 bit corresponding to 1:16384 (actual resolution: 1.36 µA)	
	<b>Maximum</b>	linearity error 0.015 %	

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<b>Memory</b>	To store important values Max/min values    Sensor 1, sensor 2, analog in Event memory      About 100 values of all status changes stored in either ring buffer or limited memory Security event memory    100 measurements before and after the security event are stored with date and time
<b>Operating temperature</b>	AC Version: -25°...+50°C    DC Version: -40°...+70°C
<b>Storage temperature</b>	-40°...+85°C
<b>Climatic immunity</b>	In accordance with DIN 40 040
<b>Relative humidity</b>	75% averaged over 1 year; up to 90% for 30 days max.
<b>Isolation</b>	Min. 1000 V
<b>EMC</b>	Electrostatic discharge: IEC 61000-4-2    Electromagnetic fields: IEC 61000-4-3 Fast transients: IEC 61000-4-4            Slow transients: IEC 61000-4-5 RF common mode: IEC 61000-4-6          Magnetic fields: IEC 61000-4-8

**Limits for limitless applications**

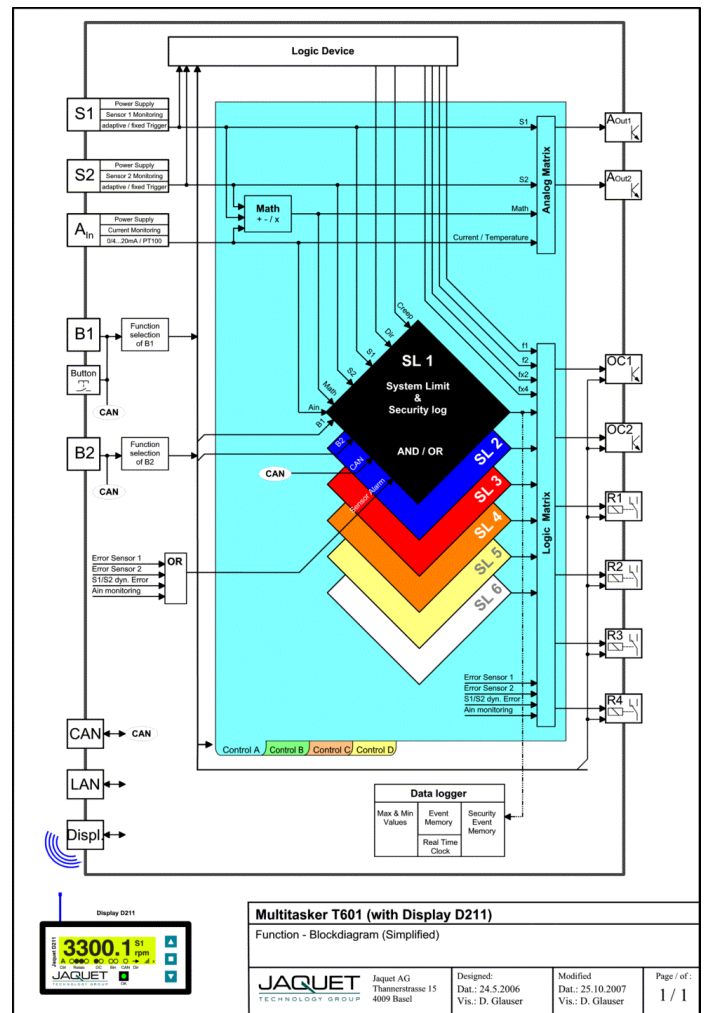
T600's allow you the freedom to choose the functions or system configuration that best match your application.

As well as being replacements for previous generation tachometers they can process multiple sensor data including frequency, 0/4...20mA analog, a directly connected PT100 temperature resistor or sensors with limit switches via binary inputs.

T600 takes T500 to a higher level. The 2 frequency inputs may either be interpreted as speed data or speed and timing signal. Logic analyses and mathematic calculations expand the possibilities.

Want to know when a trip occurred? Could you use more gear teeth than space allows? Need to swap between different parameter sets? - No problem - the T600 MultiTasker provides the solution.

Uniquely, the T600's also enables you to logically combine decision parameters from more than one sensor or command to create control signals.



## T600

Tachometer

### Display D211 (optional)

To display measured and calculated values of the T600 Multitasker. A special mode allows you also to display the status of the binary in- and outputs. The displayed values are selected with the buttons on front panel.

A LED indicates the status of the T600.

Bluetooth® version

The communication goes over Bluetooth®. One Bluetooth® Master D201 has to be connected to the T600. After that up to 7 displays D211.11 can be used to display independently different values of that T600 MultiTasker.

#### Type and part numbers

Bluetooth® version: D211.11 384Z-05730

Bluetooth® Master: D201 384Z-05731



#### Technical Data

<b>Type:</b>	5 digits LCD
<b>Range:</b>	-99'999...999'999
<b>Format:</b>	Auto range or defined dot position
<b>Displayed values:</b>	All input values, math values and current output values incl. unit
<b>Displayed status:</b>	Active control, relays, open collectors, binary inputs, CAN
<b>Mounting:</b>	Separate unit for front panel mounting
<b>Dimensions:</b>	95 x 48 x 86mm
<b>Blue tooth:</b>	Class 1 (100 m in open field)
<b>Power Supply:</b>	18...36 VDC
<b>Cable version</b>	The display is connected to the T600 MultiTasker by cable. Communication and power goes over this cable.
<b>Type and part number:</b>	
<b>Display:</b>	D211.10 384Z-05729
<b>Cable 6m</b>	304F-73740

## **T600**

Tachometer

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